

## WEST Search History

DATE: Saturday, April 05, 2003

**Set Name** **Query**  
side by side

**Hit Count** **Set Name**  
result set

*DB=USPT,PGPB,JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ*

L3	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and handle and zeus or (divinci or di vinci)	59	L3
L2	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and master handle	88	L2
L1	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and master handle and wrist joint and "5 d.o.f. or 5 dof" or five degrees of freedom	0	L1

END OF SEARCH HISTORY

**Set Name Query**  
side by side**Hit Count Set Name**  
result set*DB=USPT,PGPB,JPAB,EPAB,DWPI,TDBD; PLUR=YES; OP=ADJ*

<u>L3</u>	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and handle and zeus or (divinci or di vinci)	59	<u>L3</u>
<u>L2</u>	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and master handle	88	<u>L2</u>
<u>L1</u>	(robot\$6 or articulat\$3 or automat\$6 or autonomous\$2 or CNC or machine\$2 or mechanical device or mechan\$6 or servomechan\$4) and master handle and wrist joint and "5 d.o.f. or 5 dof" or five degrees of freedom	0	<u>L1</u>

END OF SEARCH HISTORY

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